

Lecture Notes II-2 Dynamic Games of Complete Information

- Extensive Form Representation (Game tree)
- Subgame Perfect Nash Equilibrium
- Perfect Information and Imperfect Information
- Repeated Games
- Trigger Strategy

Dynamic Games of Complete Information

- Dynamic game with complete information
 - Sequential games in which the players' **payoff functions** are common knowledge
 - **Perfect (imperfect)** information: For each move in the play of the game, the player with the move **knows (doesn't know)** the **full history** of the play of the game so far

Dynamic Game of Complete and Perfect Information

- Key features
 - (1) the moves occur in sequence
 - (2) all previous moves are observed before the next move is chosen
 - (3) the players' payoff from each feasible combination of moves are common knowledge

Backwards Induction

- A simple dynamic game of complete and perfect information
 - 1. Player 1 chooses an action a_1 from the feasible set A_1
 - 2. Player 2 observes a_1 and then chooses an action a_2 from the feasible set A_2
 - Payoffs are $u_1(a_1, a_2)$ and $u_2(a_1, a_2)$

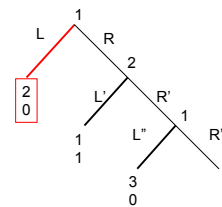
Backwards Induction (cont')

- The player 2's optimization problem in the second stage

$$\max_{a_2 \in A_2} u_2(a_1, a_2)$$
 - Assume that for each a_1 in A_1 , players' optimization problem has a unique solution, denoted by $R_2(a_1)$. This player 2's **reaction (or best response)** to player 1's action
- The player 1's optimization problem in the first stage

$$\max_{a_1 \in A_1} u_1(a_1, R_2(a_1))$$
 - Assume that this optimization problem for player 1 also has a unique solution denoted by a_1^*
 - We call $(a_1^*, R_2^*(a_1^*))$ the **backwards induction outcome** of this game

Extensive-Form Representation



⇒ In the first stage, player 1 play the optimal action **L**

Example 1: Stackelberg Model of Duopoly

- Timing of the game
 - (1) firm 1 chooses a quantity q_1
 - (2) firm 2 observes q_1 then choose a quantity q_2
- Demand function
 - $P(Q)=a-Q$, $Q=q_1+q_2$
- Profit function to firm i
 - $\pi(q_i, q_j)=q_i[P(Q)-c]$

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Example 1: Stackelberg Model of Duopoly (cont')

- In the second stage, firm 2's reaction to an arbitrary quantity by firm 1 $R_2(q_1)$ is given by solving

$$\max_{q_2 \geq 0} \pi_2(q_1, q_2) = \max_{q_2 \geq 0} q_2[a - q_1 - q_2 - c]$$

$$\Rightarrow R_2(q_1) = \frac{a - q_1 - c}{2}$$

- In the first stage, firm 1's problem is to solve

$$\max_{q_1 \geq 0} \pi_1(q_1, R_2(q_1)) = \max_{q_1 \geq 0} q_1[a - q_1 - R_2(q_1) - c] = \max_{q_1 \geq 0} q_1 \left(\frac{a - q_1 - c}{2} \right)$$

$$\Rightarrow q_1^* = \frac{a - c}{2}$$

- Outcome $q_1^* = \frac{a - c}{2}$ and $R_2(q_1^*) = \frac{a - c}{4}$

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Example 1: Stackelberg Model of Duopoly (cont')

- Compare with Nash equilibrium of the simultaneous Cournot game

Decide simultaneously

$$q_1^* = q_2^* = \frac{a - c}{3}, Q^* = \frac{2(a - c)}{3}, p = \frac{a + 2c}{3}$$

Decide sequentially

$$q_1^* = \frac{a - c}{2}, R_2(q_1^*) = \frac{a - c}{4}, Q^* = \frac{3(a - c)}{4}, p = \frac{a + 3c}{4}$$

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Example 1: Stackelberg Model of Duopoly (cont')

Decide simultaneously

$$\pi_1^* = \pi_2^* = \frac{a - c}{3} \cdot \frac{a - c}{3} = \frac{(a - c)^2}{9}$$

Decide sequentially

$$\pi_1^* = \frac{a - c}{2} \cdot \frac{a - c}{4} = \frac{(a - c)^2}{8}, \pi_2^* = \frac{a - c}{4} \cdot \frac{a - c}{4} = \frac{(a - c)^2}{16}$$

- ⇒ In single-person decision theory, having more information can never make the decision worse off. In game theory, however, having more information can make a player worse off

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Example 2: Wages and Employment in a Unionized Firm

- Timing of the game
 - (1) the union makes a wage demand, w ;
 - (2) the firm observes (and accept) w and then chooses employment L ;
 - (3) union and firm's payoffs are $U(w, L)$ and $\pi(w, L) = R(L) - wL$ respectively
 - $U(w, L)$ increases with w and L
 - $R(L)$ is increasing and concave

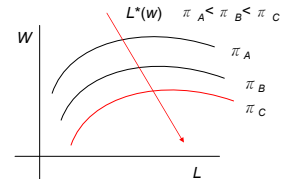
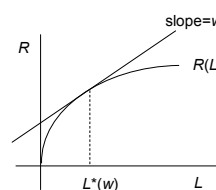
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Example 2: Wages and Employment in a Unionized Firm (cont')

In the second stage, the firm chooses $L^*(w)$ to solve

$$\max_{L \geq 0} \pi(w, L) = \max_{L \geq 0} R(L) - wL \quad \Rightarrow \quad R'(L) - w = 0$$



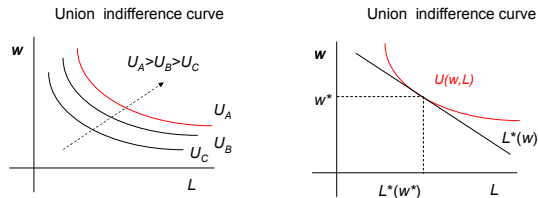
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Example 2: Wages and Employment in a Unionized Firm (cont')

In the first stage, the union chooses w^* to solve

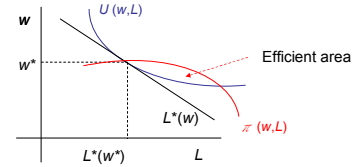
$$\max_{w \geq 0} U(w, L^*(w))$$



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Example 2: Wages and Employment in a Unionized Firm (cont')

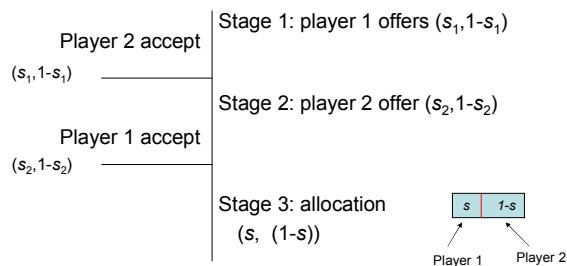


$\Rightarrow (w^*, L^*(w^*))$ is inefficient

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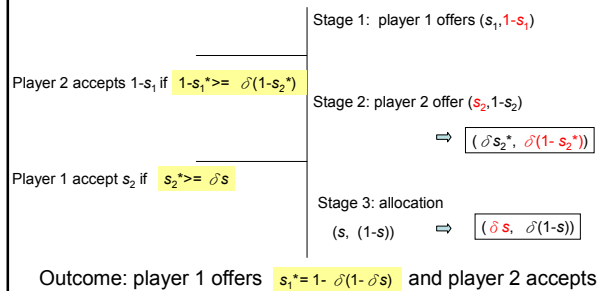
Example 3: Sequential Bargaining



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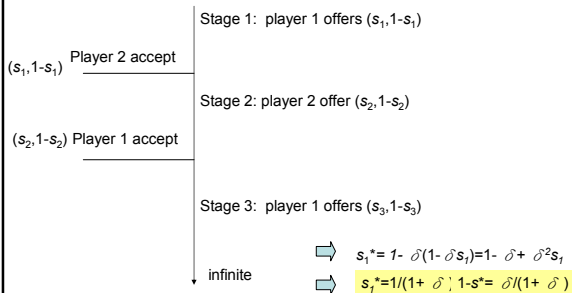
Example 3: Sequential Bargaining (cont')



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Example 3: Sequential Bargaining (cont')



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Two-Stage Game of Complete but Imperfect Information

- A two-stage game
 - Players 1 and 2 simultaneously choose actions a_1 and a_2 from feasible sets A_1 and A_2 , respectively
 - Players 3 and 4 observe the outcome of the first stage, (a_1, a_2) , and then simultaneously choose actions a_3 and a_4 from feasible sets A_3 and A_4 , respectively
 - Payoffs are $u_i(a_1, a_2, a_3, a_4)$ for $i=1,2,3,4$

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Two-Stage Game of Complete but Imperfect Information (cont')

- Backward induction
 - For any feasible outcome of the first-stage game, (a_1, a_2) , the second-stage that remains between players 3 and 4 has a unique Nash equilibrium $(a_3^*(a_1, a_2), a_4^*(a_1, a_2))$
- Subgame-perfect outcome
 - Suppose (a_1^*, a_2^*) is the unique Nash equilibrium of simultaneous-move game of player 1 and player 2
 - $(a_1^*, a_2^*, a_3^*(a_1^*, a_2^*), a_4^*(a_1^*, a_2^*))$ is called **subgame-perfect outcome**

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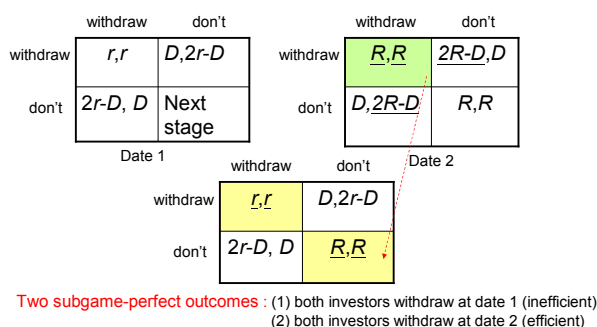
Example 1: Bank Runs

- Two investors has each deposited D with a bank
- The bank has invested these deposits in a long-term project.
 - If the bank is forced to liquidate its investment before long-term matures, a total $2r$ will be recovered
 - If the bank allows the investment to reach maturity, the project will pay out a total $2R$
 - The investors can make withdraw from bank at date 1, **before** the bank's investment mature or date 2, **after**
- Assumption : $R > D > r > D/2$

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Example 1: Bank Runs (cont')



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Example 2: Tariffs and Imperfect International Competition

- Two identical countries, denoted by $i=1,2$
- Each country has a government that chooses a tariff rate t_i , a firm that produces output for both home consumption h_i and export e_i
- If the total quantity on the market in country i is Q_i , then the market-clearing price is $P_i(Q_i) = a - Q_i$, where $Q_i = h_i + e_i$
- The total cost of production for firm i is $C_i(h_i, e_i) = c(h_i + e_i)$

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Example 2: Tariffs and Imperfect International Competition (cont')

- Timing of the game
 - First, the governments simultaneously choose tariff rates t_1 and t_2
 - Second, the firms observe the tariff rates and simultaneously choose quantities for home consumption and for export (h_1, e_1) and (h_2, e_2)
- Payoffs are profit to firm i and total welfare to government i
 - welfare = consumers' surplus + firms' profit + tariff revenue

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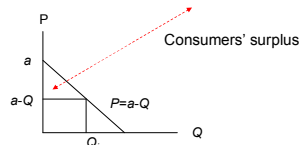
Example 2: Tariffs and Imperfect International Competition (cont')

Firm i 's profit

$$\pi_i(t_i, t_j, h_i, e_i, h_j, e_j) = [a - (h_i + e_j)]h_i + [a - (e_i + h_j)]e_i - c(h_i + e_i) - t_i e_i$$

Government i 's payoff

$$W_i(t_i, t_j, h_i, e_i, h_j, e_j) = \frac{1}{2}Q_i^2 + \pi_i(t_i, t_j, h_i, e_i, h_j, e_j) + t_i e_i$$



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Example 2: Tariffs and Imperfect International Competition (cont')

Firm i 's optimization problem

$$\max_{h_i, e_i} \pi_i(t_i, t_j, h_i, e_i, h_j^*, e_j^*)$$

$$\max_{h_i \geq 0} h_i[a - (h_i + e_j^*) - c] \Rightarrow h_j^* = \frac{1}{2}(a - e_j^* - c)$$

$$\max_{e_i \geq 0} e_i[a - (h_j^* + e_i) - c] - t_j e_i \Rightarrow e_i^* = \frac{1}{2}(a - h_j^* - c - t_j)$$

$$\Rightarrow h_i^* = \frac{a - c + t_i}{3} \quad e_i^* = \frac{a - c - 2t_i}{3}$$

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Example 2: Tariffs and Imperfect International Competition (cont')

Government i 's optimization problem

$$\max_{t_i \geq 0} W_i^*(t_i, t_j^*) = \frac{(2(a-c)-t_i)^2}{18} + \frac{(a-c+t_i)^2}{9} + \frac{(a-c-2t_j^*)^2}{9} + \frac{t_i(a-c-2t_j^*)}{3}$$

$$\Rightarrow t_i^* = \frac{a-c}{3} \quad h_i^* = \frac{a-c+t_i}{3} = \frac{4(a-c)}{9} \quad e_i^* = \frac{a-c-2t_j^*}{3} = \frac{a-c}{9}$$

$$Q_i = h_i + e_j = \frac{5(a-c)}{9}$$

Implication

$$t_i^* = 0 \Rightarrow Q_i = \frac{2(a-c)}{3} \text{ (Cournot's model), higher consumers' surplus}$$

$$\max_{t_i, t_j \geq 0} W_1^*(t_1, t_2) + W_2^*(t_2, t_1) \Rightarrow t_1^* = t_2^* = 0 \text{ (free trade)}$$

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Example 3: Tournaments

- Two workers and their boss
- Worker i produces output $y_i = e_i + \varepsilon_i$, where e_i is effort and ε_i is noise
- The workers simultaneously choose nonnegative effort levels
- The noise terms ε_1 and ε_2 are independently draws from a density $f(\varepsilon)$ with **zero mean**
- The workers' outputs are observed but their effort choices are not
- The workers' wages therefore can depend on their outputs but not (directly) on their effort

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Example 3: Tournaments (cont')

- The workers' boss decides to induce effort from the worker by having them compete in tournament
- The wage earned by the winner of the tournament is w_H , the wage earned by the loser is w_L
- The payoff to a worker from earning wage w and expending effort e is $u(w, e) = w - g(e)$, $g(e)$ is a convexly increasing function
- The payoff to the boss is $y_1 + y_2 - w_H - w_L$

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Example 3: Tournaments (cont')

Worker i 's optimization problem

$$\max_{e_i \geq 0} w = w_H \text{Prob}\{y_i(e_i) > y_j(e_j^*)\} + w_L \text{Prob}\{y_i(e_i) \leq y_j(e_j^*)\} - g(e_i)$$

$$= (w_H - w_L) \text{Prob}\{y_i(e_i) > y_j(e_j^*)\} + w_L - g(e_i)$$

First order condition

$$\frac{\partial w}{\partial e_i} = (w_H - w_L) \frac{\text{Prob}\{y_i(e_i) > y_j(e_j^*)\}}{\partial e_i} - g'(e_i)$$

$$= (w_H - w_L) \int_{\varepsilon_j} f(e_j^* - e_i + \varepsilon_j) f(\varepsilon_j) d\varepsilon_j - g'(e_i)$$

Symmetric Nash equilibrium $e_1^* = e_2^* = e^*$

$$\Rightarrow (w_H - w_L) \int_{\varepsilon_j} f(\varepsilon_j)^2 d\varepsilon_j = g'(e^*)$$

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Example 3: Tournaments (cont')

Boss's optimization problem

$$\max_{e^*} 2e^* - w_H - w_L \text{ s.t. } \frac{1}{2}w_H + \frac{1}{2}w_L - g(e^*) \geq U_a$$

$$\max_{e^*} 2e^* - 2g(e^*) - U_a$$

First order condition $1 = g'(e^*)$

$$\Rightarrow \text{Optimal wage } w_H^*, w_L^* \text{ satisfies } \begin{cases} w_H + w_L - 2g(e^*) = 2U_a \\ (w_H - w_L) \int_{\varepsilon_j} f(\varepsilon_j)^2 d\varepsilon_j = 1 \end{cases}$$

Example:

$$\text{If } f(\varepsilon) \sim N(0, \sigma^2) \Rightarrow \int_{\varepsilon_j} f(\varepsilon_j)^2 d\varepsilon_j = \frac{1}{2\sigma\sqrt{\pi}}$$

$$\Rightarrow e^* \text{ decreases with } \sigma$$

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Two-Stage Repeated Game

		Player 2	
		L_2	R_2
Player 1	L_1	1, 1	5, 0
	R_1	0, 5	4, 4

- The unique subgame-perfect outcome of the two-stage Prisoners' Dilemma is (L_1, L_2) in the first stage, followed by (L_1, L_2) in the second stage
- Cooperation, that is, (R_1, R_2) **cannot** be achieved in either stage of the subgame-perfect outcome

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Finitely Repeated Game

- Definition
 - Given a stage game G , let $G(T)$ denote the finitely repeated game in which G is played T times, with the outcomes of all preceding plays observed before the next play begins. The payoffs for $G(T)$ are simply the sum of the payoffs from the T stage games
- Proposition
 - If the stage game G has a **unique** Nash equilibrium then, for any finite T , the repeated game $G(T)$ has a **unique** subgame-perfect outcome: the Nash equilibrium of G is played in every stage

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Finitely Repeated Game with Multiple Nash Equilibrium

		Player 2		
		L_2	M_2	R_2
Player 1	L_1	1, 1	5, 0	0, 0
	M_1	0, 5	4, 4	0, 0
	R_1	0, 0	0, 0	3, 3

Two Nash equilibria (L_1, L_2) and (R_1, R_2)

Suppose the players anticipate that (R_1, R_2) will be the second-stage outcome if the first stage outcome is (M_1, M_2) , but that (L_1, L_2) will be the second-stage if any of the eight other first stage outcome occurs

		Player 2		
		L_2	M_2	R_2
Player 1	L_1	2, 2	6, 1	1, 1
	M_1	1, 6	7, 7	1, 1
	R_1	1, 1	1, 1	4, 4

Three subgame perfect Nash outcomes $((L_1, L_2), (L_1, L_2))$ with payoff (2, 2)
 $((M_1, M_2), (R_1, R_2))$ with payoff (7, 7)
 $((R_1, R_2), (L_1, L_2))$ with payoff (4, 4)

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Finitely Repeated Game with Multiple Nash Equilibrium (cont')

- Cooperation can be achieved in the first stage of a subgame-perfect outcome of the repeated game
- If G is a static game of complete information with multiple Nash equilibria then in which, for any $t < T$, there may be subgame-perfect outcome in stage t is **not** a Nash equilibrium of G
- Implication: credible threats or promises about future behavior can influence current behavior

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Infinitely Repeated Games

- **Present value**: Given the discount factor δ , the present value of the infinite sequence of payoffs, $\pi_1, \pi_2, \pi_3, \dots$ is

$$\pi_1 + \delta\pi_2 + \delta^2\pi_3 + \dots = \sum_{t=1}^{\infty} \delta^{t-1}\pi_t$$
- **Trigger strategy**: player i cooperates until someone fails to cooperate, which triggers a switch to noncooperation forever after
 - Trigger strategy is Subgame perfect Nash equilibrium when δ is sufficiently large
- **Implication**: even if the stage game has a unique Nash equilibrium, there may be subgame-perfect outcomes of the infinitely repeated game in which no stage's outcome is a Nash equilibrium

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Infinitely Repeated Games: Example

		Player 2	
		L_2	R_2
Player 1	L_1	1, 1	5, 0
	R_1	0, 5	4, 4

- Trigger strategy
 - Play R_i in the first stage. In the t^{th} stage, if the outcome of all $t-1$ preceding stages has been (R_1, R_2) then play R_i ; otherwise, play L_i

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Infinitely Repeated Games in Example (cont')

		Player 2	
		L_2	R_2
Player 1	L_1	1, 1	5, 0
	R_1	0, 5	4, 4

If any player deviates

$$V_d = 5 + \delta \cdot 1 + \delta^2 \cdot 1 + \dots = 5 + \frac{\delta}{1-\delta}$$

If no player deviates

$$V_c = \frac{4}{1-\delta} \quad (\text{Solve } V = 4 + \delta V)$$

Condition for both players to play the trigger strategy (Nash equilibrium)

$$V_c \geq V_d \Rightarrow \frac{4}{1-\delta} \geq 5 + \frac{\delta}{1-\delta} \Rightarrow \delta \geq \frac{1}{4}$$

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Infinitely Repeated Games in Example (cont')

		Player 2	
		L_2	R_2
Player 1	L_1	1, 1	5, 0
	R_1	0, 5	4, 4

- The trigger strategy is a subgame perfect Nash equilibrium (Proof)
 - The infinitely repeated game can be grouped into two classes:
 - (1) Subgame in which all the outcomes of earlier stages have been (R_1, R_2)
 - Again the trigger strategy, which is Nash equilibrium of the whole game
 - (2) Subgames in which the outcome of at least one earlier stage differs from (R_1, R_2)
 - Repeat the stage-game equilibrium (L_1, L_2) , which is also Nash equilibrium of the whole game

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Friedman Theorem (1971)

- Also called **Fork theorem**
- Theorem: Let G be a finite, static game of complete information. Let $(e_1, \dots, e_n)$ denote the payoffs from a Nash equilibrium of G , and $(x_1, \dots, x_n)$ denote any other feasible payoffs from G . If $x_i > e_i$ for every player i and if δ is sufficiently close **one**, then there exists a subgame-perfect Nash equilibrium of the infinite repeated game $G^{(\infty, \delta)}$ that achieve $(x_1, \dots, x_n)$ as the **average payoff**

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Friedman Theorem (cont')

- Feasible payoff
 - the payoff is feasible in the stage game G if they are a **convex combination** (non-negative weighted average) of the pure-strategy payoffs of G
- Example
 - By playing (L_2, R_1) or (R_1, L_2) depending on a flip of a (fair) coin, they achieve the expected payoff $(2.5, 2.5)$
 - Payoff $(2.5, 2.5)$ is feasible

		Player 2	
		L_2	R_2
Player 1	L_1	1, 1	5, 0
	R_1	0, 5	4, 4

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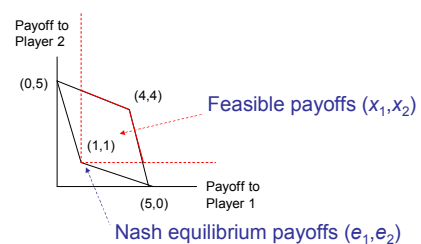
Friedman Theorem (cont')

- Notation
 - Let $(a_{e1}, \dots, a_{en})$ be the Nash equilibrium of G that yields the equilibrium payoffs $(e_1, \dots, e_n)$. Likewise, let $(a_{x1}, \dots, a_{xn})$ be the collection of actions that yields the feasible payoffs $(x_1, \dots, x_n)$
- Trigger strategy
 - For player i , play a_{xi} in the first stage. In the t th stage, if outcome of all $t-1$ proceeding stages has been $(a_{x1}, \dots, a_{xn})$ then play a_{xi} ; otherwise, play a_{ei}

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Friedman Theorem (cont')



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Friedman Theorem (cont')

Sustaining of a trigger strategy

If any player deviates

$$V_i^d = d_i + \delta \cdot e_i + \delta^2 \cdot e_i + \dots = d_i + \frac{\delta}{1-\delta} e_i$$

If no player deviates

$$V_i^c = \frac{x_i}{1-\delta} \quad (\text{Solve } V_i^c = x_i + \delta V_i^c)$$

$$V_i^c \geq V_i^d \Rightarrow \frac{x_i}{1-\delta} \geq d_i + \frac{\delta}{1-\delta} \cdot e_i \Rightarrow \delta \geq \frac{d_i - x_i}{d_i - e_i}$$

Condition for all players to play the trigger strategy

$$\Rightarrow \delta \geq \max_i \frac{d_i - x_i}{d_i - e_i}$$

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Example 1: Collusion between Cournot Duopolists

- Trigger strategy
 - Produce half monopoly quantity, $q_m/2$, in the first period. In the t th period, produce $q_m/2$ if both firms have produced $q_m/2$ in each of the $t-1$ previous periods; otherwise, produce the Cournot quantity

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Example 1: Collusion between Cournot Duopolists (cont')

$$\text{Collusion profit } \frac{\pi_m}{2} = \frac{(a-c)^2}{8} \quad \text{Competition profit } \pi_c = \frac{(a-c)^2}{9}$$

$$\text{Deviation profit } \pi_d = \frac{9(a-c)^2}{64}$$

$$\begin{aligned} \pi_d &= \max_{q_d} \left(a - q_d - \frac{1}{2} q_m - c \right) q_d \\ \text{Solve FOC } \Rightarrow q_d &= \frac{3(a-c)}{8} \\ \Rightarrow Q &= \frac{5(a-c)}{8} \\ \Rightarrow \pi_d &= \frac{3(a-c)}{8} \cdot \frac{3(a-c)}{8} \end{aligned}$$

Condition for both producer to play trigger strategy

$$\frac{1}{1-\delta} \cdot \frac{1}{2} \pi_m \geq \pi_d + \frac{\delta}{1-\delta} \cdot \pi_c \quad \Rightarrow \quad \delta \geq \frac{9}{17}$$

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Example 2: Efficiency Wages

- The firms induce workers to work hard by paying high wages and threatening to fire workers caught shirking (Shapiro and Stiglitz 1984)
- Stage game
 - First, the firms offers the worker a wage w
 - Second, the worker accepts or rejects the firm's offer
 - If the worker rejects w , then the worker becomes self-employed at wage w_0
 - If the worker accepts w , then the worker chooses either to supply effort (which entails disutility e) or to shirk (which entails no disutility)

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Example 2: Efficiency Wages (cont')

- The worker's effort decision is not observed by the firm, but the worker's output is observed by both the firm and the worker
- Output can be either high (y) or low (0)
 - If the worker supplies effort then output is sure to be high
 - If the worker shirks then output is high with probability p and low with probability $1-p$
 - Low output is an incontrovertible sign of shirking
- Payoffs: Suppose the firm employs the worker at wage w
 - if the worker supplies effort and output is high, the payoff of the firm is $y-w$ and payoff of the worker is $w-e$
- Efficient employment
 - $y-e > w_0 > py$

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Example 2: Efficiency Wages (cont')

- Subgame-perfect outcome
 - The firm offer $w=0$ and the worker chooses self-employment
 - The firms pays in advance, the worker has no incentive to supply effort
- Trigger strategy as repeated-game incentives
 - The firm's strategy: offer $w=w^*$ ($w^* > w_0$) in the first period, and in each subsequent period to offer $w=w^*$ provided that the history of play is high-wage, high-output, but to offer $w=0$, otherwise
 - The worker's strategy: accept the firm's offer if $w > w_0$ (choosing self-employment otherwise) the history of play, is high-wage, high-output (shirking otherwise)

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Example 2: Efficiency Wages (cont')

- If it is optimal for the worker to supply effort, then the present value of the worker's payoff is

$$V_e = (w^* - e) + \delta V_e \Rightarrow V_e = (w^* - e) / (1 - \delta)$$

- If it is optimal for the worker to shirk, then the (expected) present value of the worker's payoffs is

$$V_s = w^* + \delta \left\{ pV_s + (1-p) \frac{w_0}{1-\delta} \right\} \Rightarrow V_s = \frac{(1-\delta)w^* + \delta(1-p)w_0}{(1-\delta p)(1-\delta)}$$

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Example 2: Efficiency Wages (cont')

- It is optimal for the worker to supply effort if

$$V_e \geq V_s \Rightarrow w^* \geq w_0 + \frac{(1-p\delta)e}{\delta(1-p)} = w_0 + \left(1 + \frac{1-\delta}{\delta(1-p)}\right)e$$

- The firm's strategy is a best response to the worker's if

$$y > w^* \geq 0$$

- We assume $y - e > w_0$, the SPNE implies

$$y - e \geq w_0 + \frac{(1-\delta)e}{\delta(1-p)}$$

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Example 3: Time-Consistent Monetary Policy

- Consider a sequential-move game in which employers and workers negotiate nominal wages, after which the monetary authority chooses the money supply, which in turn determined the rate of inflation
- Employers and workers will try to anticipate inflation in setting the wage
- Actual inflation above the anticipated level of inflation will erode the wage, causing employers to expand employment
- The monetary authority therefore faces a trade-off between the costs of inflation and benefits of reduced unemployment

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Example 3: Time-Consistent Monetary Policy (cont')

- The model (Barro and Gordon 1983)
- First, employers form an expectation of inflation, π^e . Second, the monetary authority observes this expectation and chooses actual inflation π .
- The payoff to employers is $-(\pi^e - \pi)^2$
 - Employers achieve maximum payoff when anticipate inflation correctly
- The payoff to the monetary authority

$$U(\pi, y) = -c\pi^2 - (y - y^*)^2$$
 The monetary authority would like inflation to be zero but output (y) to be at its efficient level (y^*)

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Example 3: Time-Consistent Monetary Policy (cont')

- Suppose that actual output is the following function of target output and surprise inflation:

$$y = by^* + d(\pi - \pi^e)^2, \quad b < 1, \quad d > 0$$

- The monetary authority's payoff can be rewritten as

$$W(\pi, \pi^e) = -c\pi^2 - [(b-1)y^* + d(\pi - \pi^e)]^2$$

$$\frac{\partial W}{\partial \pi} = 0 \Rightarrow \pi^*(\pi^e) = \frac{d}{c+d^2} [(1-b)y^* + d\pi^e]$$

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Example 3: Time-Consistent Monetary Policy (cont')

- Employers anticipate that the monetary authority will choose $\pi^*(\pi^e)$, employers choose π^e to maximize $-[\pi^*(\pi^e) - \pi^e]^2$

$$\pi^*(\pi^e) = \pi^e \Rightarrow \pi^e = \frac{d(1-b)}{c} y^* = \pi_s$$

- The monetary authority's payoff can be rewritten as

$$W(\pi, \pi^e) = -c\pi^2 - [(b-1)y^*]^2$$

$$\text{if } \pi = 0 \Rightarrow W(\pi, \pi^e) \text{ is maximized}$$

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Example 3: Time-Consistent Monetary Policy (cont')

- Consider the infinitely repeated game in which both players share the discount factor δ
- Derive conditions under which $\pi^e = \pi^s = 0$, in every period is a subgame-perfect Nash equilibrium
 - The employer hold the expectation $\pi^e = 0$ provided that all prior actual inflations have been $\pi = 0$. Otherwise, the employer hold the expectation $\pi^e = \pi_s$
 - The monetary authority set $\pi = 0$ provided all prior expectations have been $\pi^e = 0$. Otherwise, The monetary authority set $\pi = \pi^*(\pi^e)$

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Example 3: Time-Consistent Monetary Policy (cont')

- The monetary authority's strategy is a best response to the employers' updating rule if

$$\frac{1}{1-\delta} W(0,0) \geq W(\pi^*(0),0) + \frac{\delta}{1-\delta} W(\pi_s, \pi_s)$$

$$\Rightarrow \delta \geq \frac{c}{(2c+d^2)}$$

$$\frac{\partial \delta}{\partial c} > 0; \frac{\partial \delta}{\partial d} < 0$$

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Practice: Create your own ideas

- Propose IT/IS applications, utilizing tournaments model
 - Competition rule
 - Uncertain factor
 - Effort and outcome functions
- Propose IT/IS applications, utilizing reliability/free-riding model
 - Commons (public goods) function
 - Individual (Nash) and Efficient (Social optimum) results
 - Incentive mechanism (fine, liability)
- IT/IS applications include EC, KM, SCM, ... etc.
- Grading: will be considered to improve your participation parts
- When to submit : two weeks from today

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Extensive-Form Representation of Games

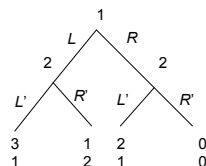
- Definition: the extensive-form representation of a game specifies:
 - (1) the players in the game
 - (2a) **when** each player has the move
 - (2b) **what** each player **can do** at each of his or her opportunities to move
 - (2c) **what** each player **knows** at each of his or her opportunities to move, and
 - (3) the **payoff** received by each player for each combination of moves that could be chosen by the players

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Extensive-Form Representation of Games (cont')

- Player 1 chooses an action a_1 from the feasible set $A_1 = \{L, R\}$
- Player 2 observes a_1 and then chooses an action a_2 from the set $A_2 = \{L', R'\}$
- Payoffs are $u_1(a_1, a_2)$ and $u_2(a_1, a_2)$, as shown in the game tree



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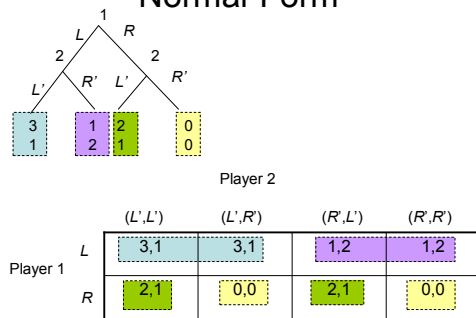
Extensive-Form Representation of Games (cont')

- Definition: A **strategy** for a player is a **complete plan of actions** – it specifies a feasible **action** for the player in every contingency in which the player might be called on to act
- Action vs. strategy
 - Player 2 has 2 actions $A_2 = \{L', R'\}$ but 4 strategies $S_2 = \{(L', L'), (L', R'), (R', L'), (R', R')\}$
 - (L', L') : if player 1 play L (R), then play L' (L')
 - (L', R') : if player 1 play L (R), then play L' (R')
 - (R', L') : if player 1 play L (R), then play R' (L')
 - (R', R') : if player 1 play L (R), then play R' (R')
 - Player 1 has 2 actions $A_1 = \{L, R\}$ also has 2 strategies $S_1 = \{L, R\}$

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Transform Extensive-Form to Normal-Form



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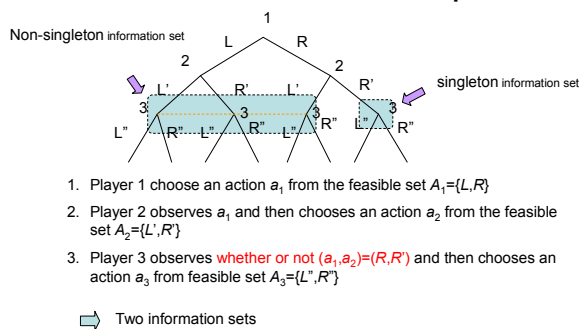
Information Set

- Definition: An information set for a player is a collection of decision nodes satisfying
 - (i) the player **has the move at every node** in the information set, and
 - (ii) when the play of the game reaches a node in the information set, and the player with the move **does not know** which node in the information set has (or has not) been reached

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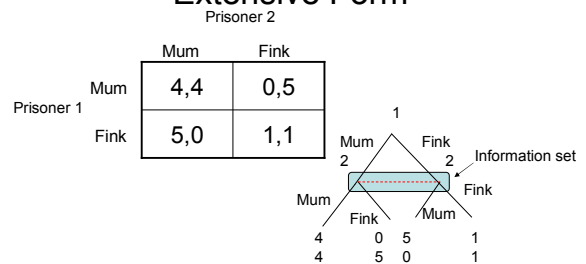
Information Set: Example



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Transform Normal Form to Extensive Form



Interpretation of Prisoner 2's information set : when Prisoner 2 gets the move, all he know is that the **information set** has been reached (**that prisoner 1 has move**), **not which node** been reached (**what prisoner 1 did**)

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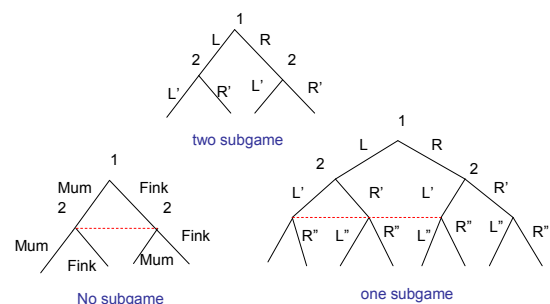
Subgame: Definition

- Definition : A subgame is an extensive-form game
 - (a) begins at a decision node n that is a **singleton information set** (but is not the game's first decision node)
 - (b) **includes all the decision and terminal nodes following n** in the game tree (but no nodes that do not follow n), and
 - (c) **does not cut any information sets** (i.e. if a decision node n' follows n in the game tree, then all other nodes in the information set containing n' must also follow n , and so must be included in the subgame)

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Subgame : Example



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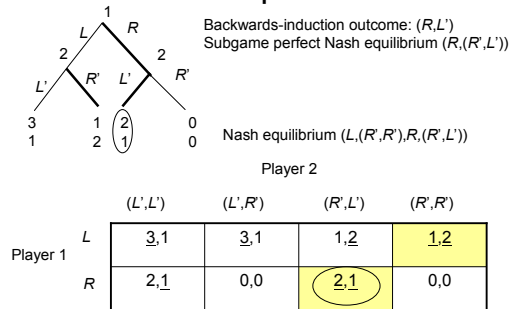
Subgame-Perfect Nash Equilibrium vs. Outcome

- Definition: (Selten 1965) A Nash equilibrium is **subgame-perfect** if the players' strategies constitute a **Nash equilibrium in every subgame**
 - Equilibrium is a collection of strategies (and strategy is a complete plan of action), whereas an **outcome** describes what will happen only in the contingency that are expected to arise, not in every contingency that might arise
 - In the two-stage game of complete and perfect information, the **backwards-induction outcome** is $(a_1^*, R_2(a_1^*))$ but the **subgame-perfect Nash equilibrium** is $(a_1^*, R_2(a_1^*))$. $R_2(a_1^*)$ is an action and $R_2(a_1^*)$ is a strategy (best response function) for player 2

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Subgame Perfect Nash Equilibrium vs. Nash Equilibrium



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Subgame perfect Nash equilibrium v. Nash equilibrium (cont')

- Subgame-perfection eliminates Nash equilibria that rely on noncredible threats or promise
 - $(L, (R', R'))$: player 2's strategy is to play R' not only if player 1 chooses L but also if player 1 chooses R
 - The Nash equilibrium $(L, (R', R'))$ is not a subgame-perfect since player 2's choice of R' (with payoff 0) is not optimal in the subgame beginning at player 2's decision node following R by player 1 (optimal choice is L' with payoff 1)

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Homework #2

- Problem set
 - 3, 6, 8, 14, 17, 20 (from Gibbons)
- Due date
 - two weeks from current class meeting
- Bonus credit
 - Propose new applications in the context of IT/IS or potential extensions from examples discussed

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